



One-Dimensional Haptic Rendering Device based on an Audio Loudspeaker

R. Lee, A. Marcovici, A. Khera, Z. Yu, R. Klatzky, M. Siegel, S. G. Shroff, and G. Stetten

- Direct electromagnetic actuation
- Independent force and displacement measurement
- High bandwidth
- Low latency
- Low mass
- Low friction
- Dedicated microprocessor for tissue models with PID control
- Render tool-tissue interaction
- Inexpensive

